

AC M2n

AC servo motors



**Product
Manual**

Further descriptions, that relate to this document:

UL: 05-01-05



Planetary Gearbox PG A - Product-manual

UL: 05-01-06



Planetary Gearbox PG AL - Product-manual

UL: 05-01-07



Planetary Gearbox PG AF - Product-manual

UL: 12-01



Plugs - Product description

UL: 12-02-01



Cables - Product description

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Made in Germany, 2004

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The most important thing first

Thanks for your confidence choosing our product.

These operating instructions present themselves as an overview of the technical data and features.

Please read the operating instructions before operating the product.

If you have any questions, please contact your nearest SSD Drives representative. Improper application of the product in combination with dangerous voltage can lead to injuries.

In addition, damage can also occur to motors or other products.

Therefore please observe our safety precautions strictly.

Safety precautions

We assume that, as an expert, you are familiar with the relevant safety regulations, especially in accordance with VDE 0100, VDE 0113, VDE 0160, EN 50178, the accident prevention regulations of the employers liability insurance company and the DIN regulations and that you are able to use and apply them.

As well, relevant European Directives must be observed.

Depending on the kind of application, additional regulations e.g. UL, DIN are subject to be observed.

If our products are operated in connection with components from other manufacturers, their operating instructions are also subject to be observed strictly.

1 General

1.1 Description

By using high-energy magnetic materials it is possible to design small diameter disk motors. For this reason and due to a carefully optimized technical construction of the rotor, the motors have a low moment of inertia.

The stability of the magnetic material and the design of the magnetic field in the face of demagnetization allow maximum currents of up to **3- 4 times the rated current**.

The high acceleration capacity of the low-inertia three-phase AC servo drives is the result of this.

Through the excitation of the permanent magnets, no heat losses due to current occur in the rotor.

With the three-phase AC-servomotors heat losses due to current occur only in the stator, which then can be directly drawn off.

These favorable cooling conditions allow high-capacity windings.

Since all the current heat losses are drawn off directly via the surface, the motors are designed at low cost with the enclosure type providing protection in accordance with **IP xx** and they are thus very insensitive to liquids and dirt.

The resolver is built into the B-side bearing bracket.

The signals of this integrated measuring system for the actual speed value, the rotor position and the indirect position are taken at the motor over a 12-pin connector.

Synchronous three-phase AC servo drives have a series of advantages over the DC drives:

- no electromechanical parts to wear out, therefore "maintenance-free".
- a low moment of inertia of the rotor due to power density, therefore high acceleration capacity.
- no commutation limit curve, therefore high acceleration moments, also in higher speed ranges.
- no losses in the rotor of the motor, therefore favorable thermal characteristics and a high degree of protection due to the closed construction.

Three-phase AC servomotors built in the way described, are specifically more efficient (higher rated torque) than DC servomotors and also have a small inertia. Therefore the size necessary for an application will, for this reason, be smaller with three-phase AC servos than with DC servos.

Important !

- The motor series AC G is not attachment- or pin-compatible to our drives AC M or AC R.
- Motor design AC G only in standard.

General

1.2 Type code

Marking	Standard						optional	
	a	b	c	d	e	f	g	h
Type:	AC	XXX	XXXX	-X	/X	-X	XX	+ ...

Marking	Description
a	AC = three-phase
b	motor models: <u>G</u> = motor series <u>G</u> without cases <u>M</u> = motor series (old) <u>Mn</u> = motor series <u>n</u> ew <u>M2n</u> = motor series 2 nd <u>n</u> ew version <u>MHS</u> = motor series <u>H</u> iperface <u>S</u> ingleturn (under preparation) <u>MHM</u> = motor series <u>H</u> iperface <u>M</u> ultiturn <u>R</u> = motor series <u>R</u> <u>R(L)</u> = motor series <u>RL</u> with separate fan
c	<u>xxxx</u> = approx. rated torque in Ncm
d	-4 = 4000 rpm at motor type: "AC <u>G</u> ; AC <u>Mn</u> ; AC <u>M2n</u> ; AC <u>MHx</u> " 1..6 = *1000 1/min at motor type: "AC <u>R</u> " -X = further on request (designation does not apply with motor / gearbox systems)
e	/Y..4 = motor size (designation does not apply with motor / gearbox systems)
f	-3 = 325 V DC intermediate circuit rated voltage ($\cong$ 230 VAC) -6 = 565 V DC intermediate circuit rated voltage ($\cong$ 400 VAC)
g	identification for <u>options</u> and custom features XX = see chapter 1.3
h	+ ... = with attached gear-box: (for short description for inserted gearbox models see gearbox documentation)

Note:

Up to marking "g" it is only necessary with options or custom features.

No options are possible for the AC G drive.

1.2.1 Typical example

A typical example of an order corresponding to the model key would be:

Type: AC <u>G</u> 0090-4/01-3	Type: AC <u>M2n</u> 0090-4/1-3	Type: AC <u>R</u> 0095-6/1-3
AC = three phase	AC = three phase	AC = three phase
<u>G</u> = motor series	<u>M2n</u> = motor series 2 nd new version	<u>R</u> = motor series
0090 = rated torque in Ncm	0090 = rated torque in Ncm	0068 = rated torque in Ncm
-4 = 4000 rpm	-4 = 4000 rpm	-6 = 6000 rpm
/01 = motor size	/1 = motor size	/1 = motor size
-3 = 325V DC (230 VAC)	-3 = 325V DC	-3 = 325V DC

General

1.3 Possible options (Marking: g)

Marking	Options			and Marking	Description	motor types			
	BR	GW	IP 65			A C G	A C M n	A C M 2n	A C R
GW		X			smooth motor shaft	☐	☒	☒	☒
BR	X				holding brake, 24V DC	☐	☒	☒	☒
BBR	X				holding brake type B 24V DC	☐	☐	☒	☒
65			X		degree of protection IP 65	☐	☒	☒	☒
BG	X	X				☐	☒	☒	☒
AI					absolute or incremental encoder preparation of attachment	☐	☒	☒	☒
BI	X			AI		☐	☒	☒	☐
PL					electrical connections via PG couplings and cable ends	☐	☒	☒	☒
2P					2 nd featherkey way	☐	☒	☒	☒
6P			X	2P		☐	☒	☒	☒
90					flange receptacle for motor and resolver 90° angled	☐	☒	☒	☐
GP		X		PL		☐	☒	☒	☐
G6		X	X			☐	☒	☒	☒
MS					mech. custom designs	☐	☒	☒	☒
PU				PL	unpainted motor	☐	☒	☒	☒
PS		X		PU		☐	☒	☒	☐
SL					special finish	☐	☒	☒	☒
GK		X			smooth motor shaft shortend	☐	☒	☒	☒
VA	X	X		PL		☐	☒	☒	☐
R6			X		rust-proof motor shaft	☐	☒	☒	☐
P6			X	PL		☐	☒	☒	☐
B6	X		X			☐	☒	☒	☒
F6			X		flange receptacle B-side	☐	☒	☒	☐
VI	X	X		AI		☐	☒	☒	☒
GI		X		AI		☐	☒	☒	☒
V6	X	X	X			☐	☒	☒	☒
L6		X	X	PL		☐	☒	☒	☐
BL	X		X	PL		☐	☒	☒	☐
B4	X				flange B 14	☐	☒	☒	☐
VR		X		PL+R6+AI		☐	☒	☒	☐
S6			X	PL+R6+2P		☐	☒	☒	☐
GZ		X			with Centre hole	☐	☒	☒	☐
N6		X	X		with special rotation speed about software (6000)	☐	☒	☒	☐
HW		X			with Hollow shaft	☐	☒	☒	☐
T6			X		for tropical climate	☐	☒	☒	☐
X6				F6 + 2P		☐	☒	☒	☐

* only motor size 3

- standard design
- ◐ optional
- not possible

2 General technical data

		A C	A C	A C	A C
		G	M n	M 2 n	R
Degree of protection: with mounted mating connectors and built-on motor	IP44 (with separate fan)	☐	☐	☐	☒
	IP54	☒	☒	☒	☐
	IP65	☐	☒	☒	☒
Magnetic material:	NdFeB	☒	☒	☒	☐
	SE	☐	☐	☐	☒
Electrical connections:	straight flanged sockets	☐	☒	☐	☒
	rotatable 90° angled for motor-, resolver- and thermal connection-flanged sockets	☒	☐	☒	☐
	PG couplings with cable ends	☒	☒	☒	☐
Thermal protection of motor:	thermal detector PTC	☒	☒	☒	☒
Power:	In accordance with DIN VDE 0530 installation site: 1000 ASL T = 100K, Tu 40°C measured with attached cooling surface	☒	☒	☒	☒
Voltage:	325 V DC	☒	☒	☒	☒
	565 V DC	☐	☒	☒	☒
	other windings are possible.	☐	☒	☒	☐
Cooling:	self-cooling	☒	☒	☒	☒
	separate cooling	☐	☐	☐	☒
Operating mode:	Continuous operation S1	☒	☒	☒	☒
Bearings:	Ball bearings, service life approx. 15.000 h	☒	☒	☒	☒
Motor shaft: (standard)	with fitting key in accordance with DIN 6885	☒	☒	☒	☒
Rotational accuracy:	N, in acc. with DIN ISO 2373	☒	☒	☒	☒
Number of pole pairs:	2	☐	☐	☐	★
	3	☒	☒	☒	★
Resolver type:	2 pole SSD Drives transmitter resolver	☒	☒	☒	☐
	2 pole standard transmitter resolver	☐	☐	☐	☒
Insulation class	F (VDE 0530) 155° C, heating 100° K	☒	☒	☒	☒
Varnish: (standard)	similar RAL 9005 (black)	☒	☒	☒	☒

- standard design
- ◐ optional
- not possible

- ★ dependent on size
- ◆ only with larger quantities

3 Technical data

Type: AC M2n

AC-Servo motor Type:	size	Technical data				Static torque	Static current	max. Static torque	Moment of inertia included resolver
		Nominal power	Rated torque	Rated current with					
				325V DC	565V DC				
		P _N (KW)	M _N (Nm)	I _{N325} (A)	I _{N565} (A)	M ₀ (Nm)	I ₀ (A)	M _{0max} (Nm)	J _M (kgcm ²)
AC M2n0012-6/Y-3	¹⁾ Y	0,075	0,12	0,33	-	0,16	0,44	0,64	0,05
AC M2n0010-4/0-3	0	0,040	0,10	0,20	-	0,13	0,25	0,52	0,05
AC M2n0030-4/0-3		0,126	0,30	0,80	-	0,30	0,90	1,20	0,10
AC M2n0045-4/0-3		0,189	0,45	1,08	-	0,50	1,20	2,00	0,15
AC M2n0045-4/0-6		0,189	0,45	-	0,60	0,50	0,65	2,00	0,15
AC M2n0070-4/0-3		0,293	0,70	1,46	-	0,80	1,60	3,20	0,20
AC M2n0070-4/0-6		0,293	0,70	-	0,82	0,80	0,90	3,20	0,20
AC M2n0130-4/0-3	¹⁾	0,545	1,30	2,80	-	1,50	3,30	6,00	0,33
AC M2n0130-4/0-6	¹⁾	0,545	1,30	-	1,40	1,50	1,65	6,00	0,33
AC M2n0055-4/1-3	1	0,230	0,55	1,40	-	0,80	2,10	3,20	0,30
AC M2n0055-4/1-6		0,230	0,55	-	0,76	0,80	1,20	3,20	0,30
AC M2n0090-4/1-3		0,377	0,90	1,80	-	1,50	3,00	6,00	0,68
AC M2n0090-4/1-6		0,377	0,90	-	1,10	1,50	1,80	6,00	0,68
AC M2n0150-4/1-3		0,628	1,50	3,00	-	2,50	5,00	10,00	1,00
AC M2n0150-4/1-6		0,628	1,50	-	1,90	2,50	2,70	10,00	1,00
AC M2n0220-4/1-3		0,922	2,20	4,70	-	3,00	6,40	12,00	1,40
AC M2n0220-4/1-6		0,922	2,20	-	2,80	3,00	3,80	12,00	1,40
AC M2n0290-4/1-3		1,215	2,90	6,00	-	4,00	8,30	16,00	1,80
AC M2n0290-4/1-6		1,215	2,90	-	3,00	4,00	4,20	16,00	1,80
AC M2n0320-4/2-3	2	1,340	3,20	6,40	-	4,00	8,20	16,00	2,40
AC M2n0320-4/2-6		1,340	3,20	-	3,60	4,00	4,50	16,00	2,40
AC M2n0480-4/2-3		2,010	4,80	9,80	-	7,00	14,30	28,00	3,20
AC M2n0480-4/2-6		2,010	4,80	-	4,90	7,00	7,20	28,00	3,20
AC M2n0650-4/2-3		2,720	6,50	13,20	-	9,00	18,30	36,00	3,60
AC M2n0650-4/2-6		2,720	6,50	-	6,60	9,00	9,20	36,00	3,60
AC M2n0830-4/2-6		3,480	8,30	-	9,30	11,00	12,30	44,00	4,50
AC M2n0960-4/3-6	²⁾ 3	4,020	9,60	-	11,00	16,00	18,40	64,00	6,15
AC M2n1200-4/3-6	²⁾	5,030	12,00	-	16,00	21,00	28,00	84,00	7,70
AC M2n2000-4/3-6	²⁾	8,370	20,00	-	19,30	34,00	33,00	136,00	12,50

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Size Y Data at rated speed of 6000 rpm

Size 0 -3 Data at rated speed of 4000 rpm

¹⁾ not with holding brake equip !

²⁾ The servo motors possess approx. 10 - 15% higher moment of inertia (J_M), in the middle of 2003.

Technical data

Type: AC M2n

AC-Servo motor Type:	size	Mass	Motor resistance	Motor inductance	Thermal time constant		Torque constant	e.m.f constant eff.
		m (kg)	Rph/ph (Ω)	Lph/ph (mH)	T _{thN} (min)	T _{thmax} (s)	K _T (Nm/A)	K _E (V/1000 min-1)
AC M2n0012-6/Y-3	¹⁾ Y	1,01	35,00	22,00	11	28	0,38	23
AC M2n0010-4/0-3	0	0,83	122,00	66,00	7	18	0,50	30
AC M2n0030-4/0-3		1,30	18,30	13,00	10	26	0,40	26
AC M2n0045-4/0-3		1,60	12,00	14,30	12	31	0,41	28
AC M2n0045-4/0-6		1,60	32,00	28,00	12	31	0,74	47
AC M2n0070-4/0-3	¹⁾	1,90	8,90	9,30	14	36	0,50	28
AC M2n0070-4/0-6		1,90	27,70	23,00	14	36	0,83	50
AC M2n0130-4/0-3		2,80	3,80	4,60	14	36	0,46	28
AC M2n0130-4/0-6		2,80	13,70	13,90	14	36	0,92	51
AC M2n0055-4/1-3	1	2,00	6,30	14,30	20	51	0,39	26
AC M2n0055-4/1-6		2,00	18,40	39,00	20	51	0,66	44
AC M2n0090-4/1-3		2,90	3,10	9,20	20	51	0,50	30
AC M2n0090-4/1-6		2,90	7,70	24,00	20	51	0,83	50
AC M2n0150-4/1-3		3,70	1,70	6,00	23	59	0,50	30
AC M2n0150-4/1-6		3,70	5,20	16,70	23	59	0,94	59
AC M2n0220-4/1-3		4,30	1,10	4,30	26	66	0,50	33,5
AC M2n0220-4/1-6		4,30	2,80	11,00	26	66	0,83	52
AC M2n0290-4/1-3		5,30	0,80	3,20	30	77	0,48	33
AC M2n0290-4/1-6		5,30	2,40	9,30	30	77	0,97	55
AC M2n0320-4/2-3	2	6,00	1,00	5,50	19	49	0,49	35
AC M2n0320-4/2-6		6,00	2,80	13,60	19	49	0,98	60
AC M2n0480-4/2-3		7,60	0,40	2,30	29	74	0,49	30
AC M2n0480-4/2-6		7,60	2,00	11,30	29	74	0,98	68
AC M2n0650-4/2-3		8,50	0,47	1,90	38	97	0,49	33
AC M2n0650-4/2-6		8,50	1,30	7,60	38	97	0,98	60
AC M2n0830-4/2-6		16,00	0,80	4,70	50	128	0,89	54
AC M2n0960-4/3-6	3	19,50	0,60	6,10	36	92	0,87	58
AC M2n1200-4/3-6		22,00	0,30	3,20	52	133	0,75	48
AC M2n2000-4/3-6		30,00	0,30	3,80	88	225	1,04	65

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$$K_T \approx K_{T_0} \approx K_{T_N}$$

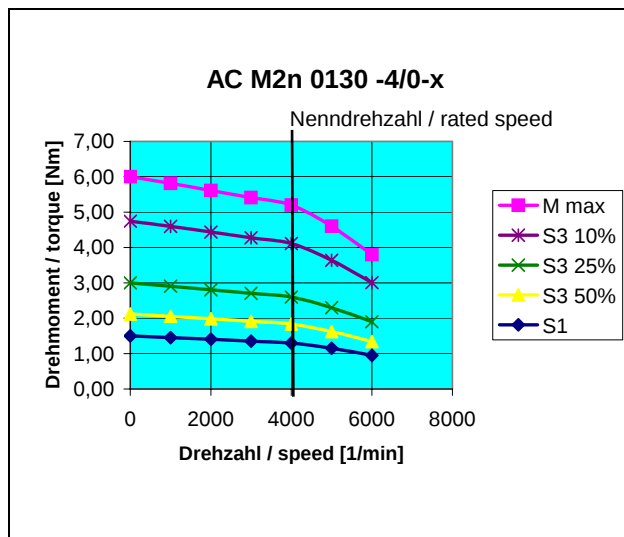
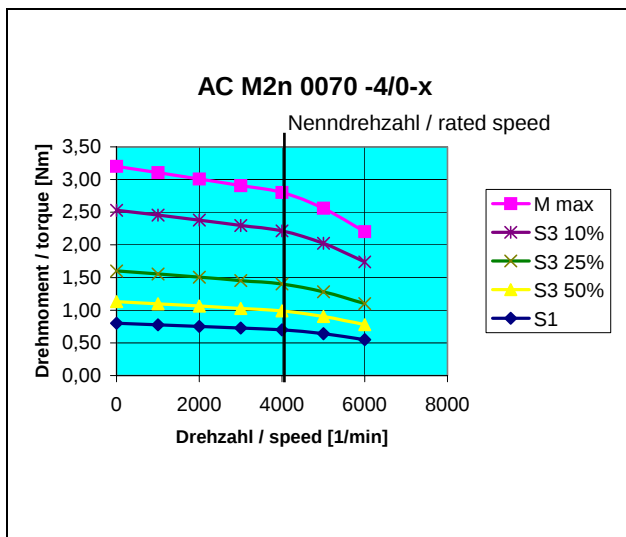
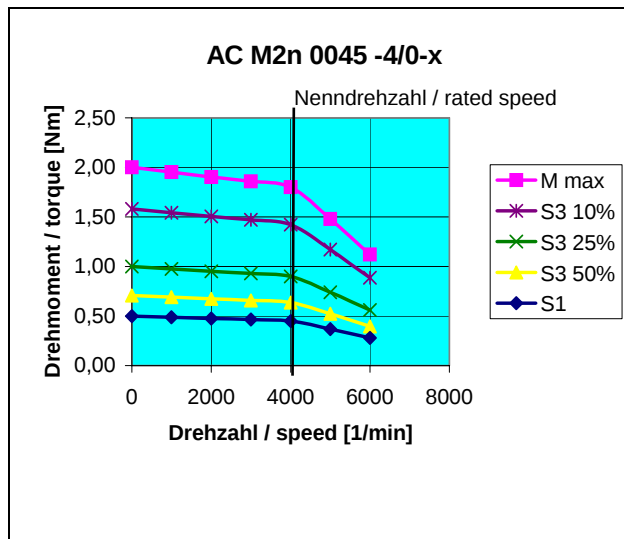
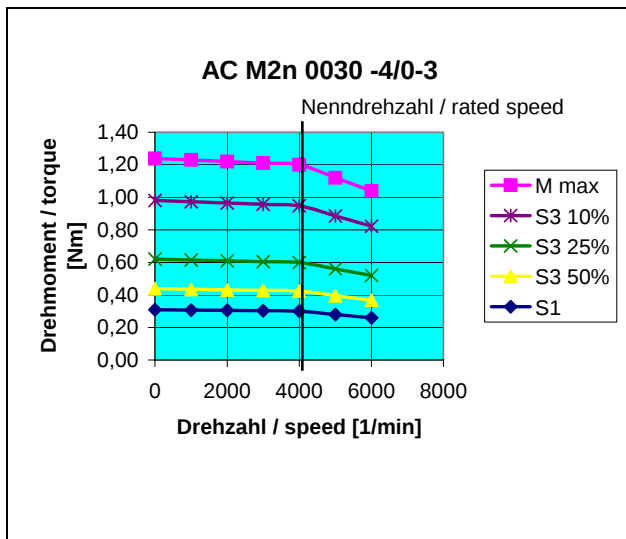
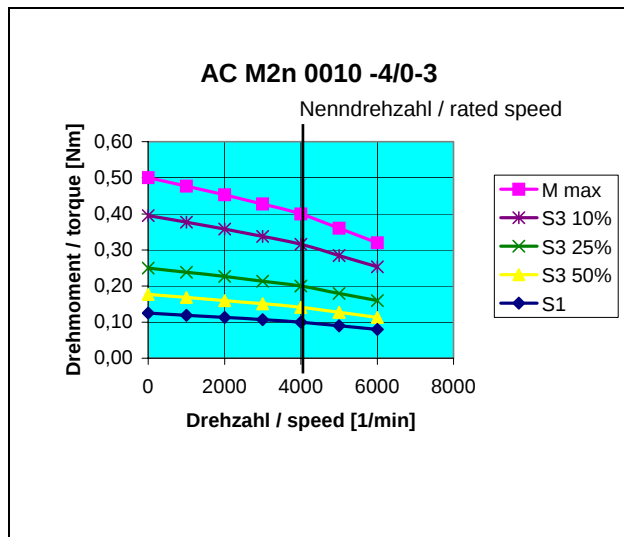
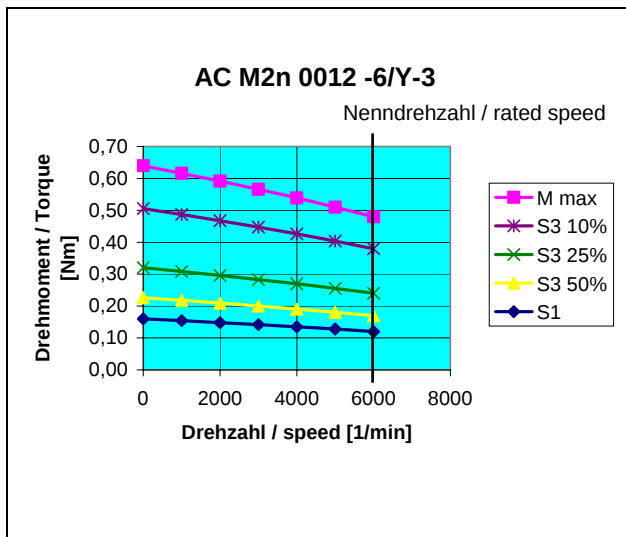
Size Y Data at rated speed of 6000 rpm
Size 0 – 3 Data at rated speed of 4000 rpm

¹⁾ not with holding brake equip !

Technical data

3.1 Torque/Speed Diagrams

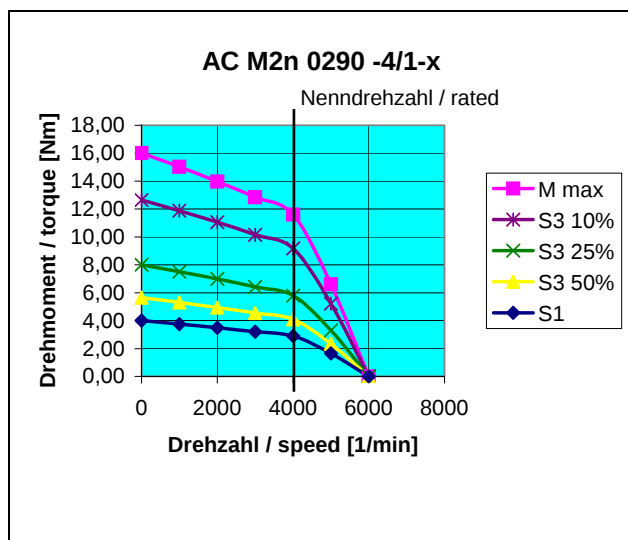
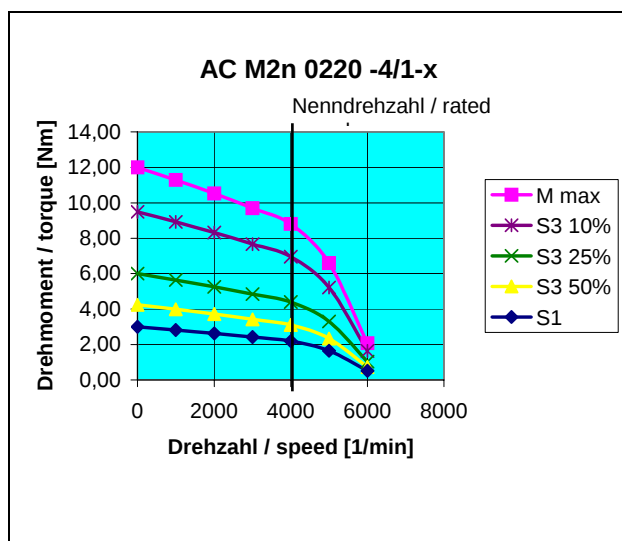
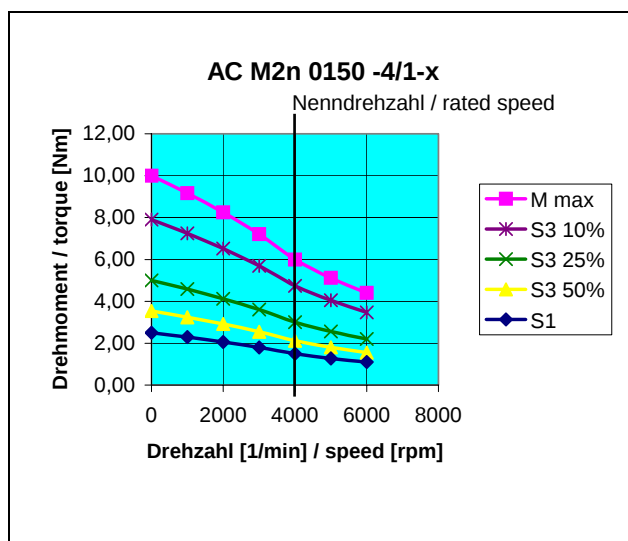
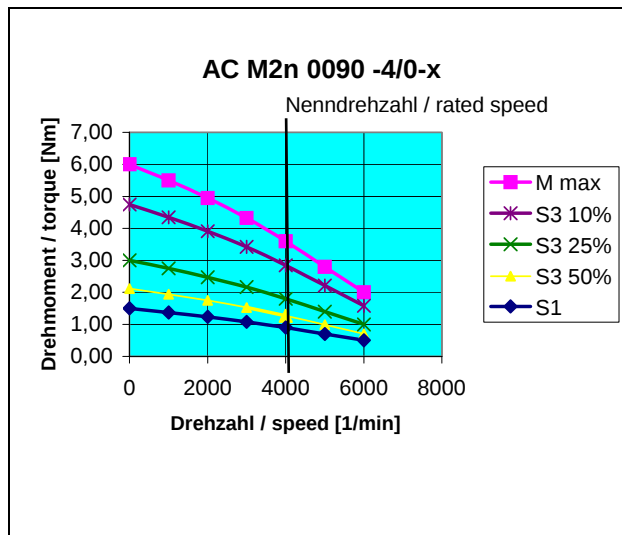
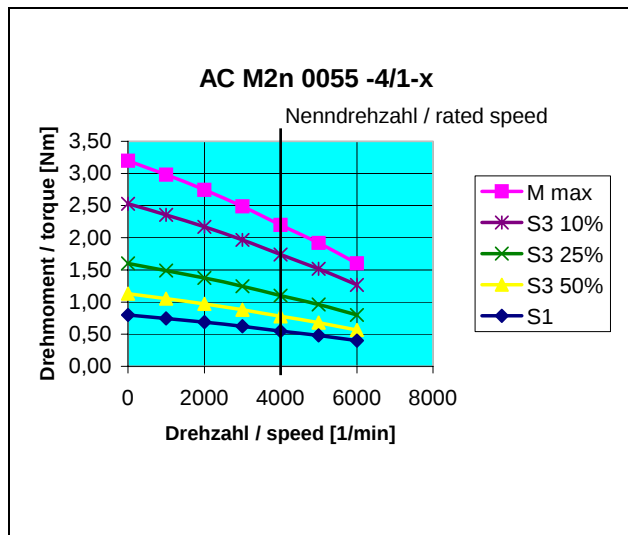
3.1.1 Motor size Y and 0



Technical data

Torque/Speed Diagrams

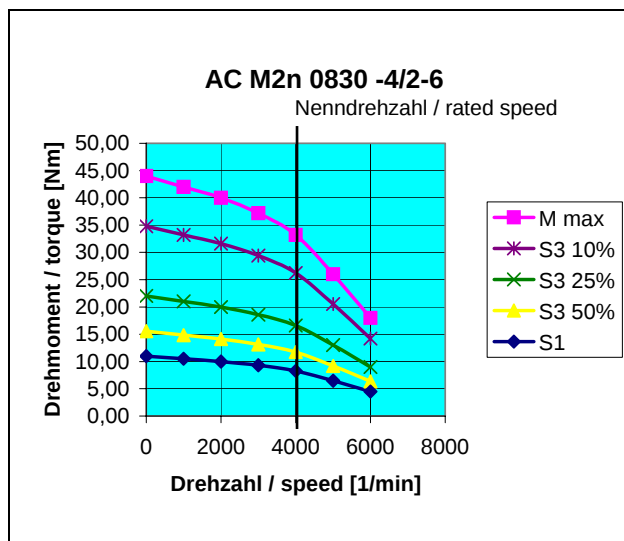
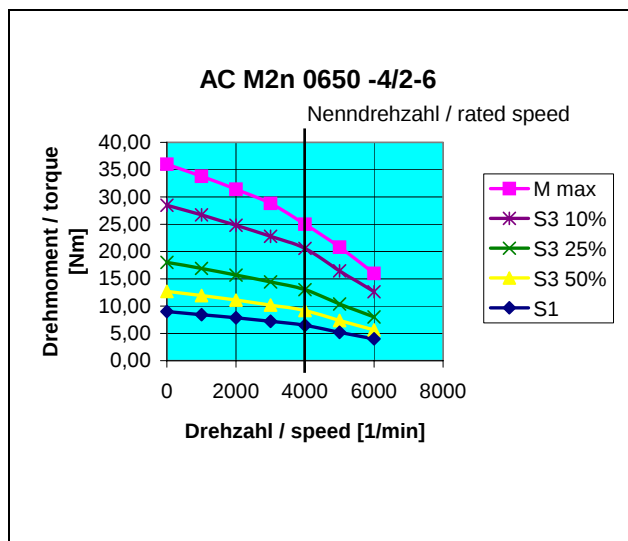
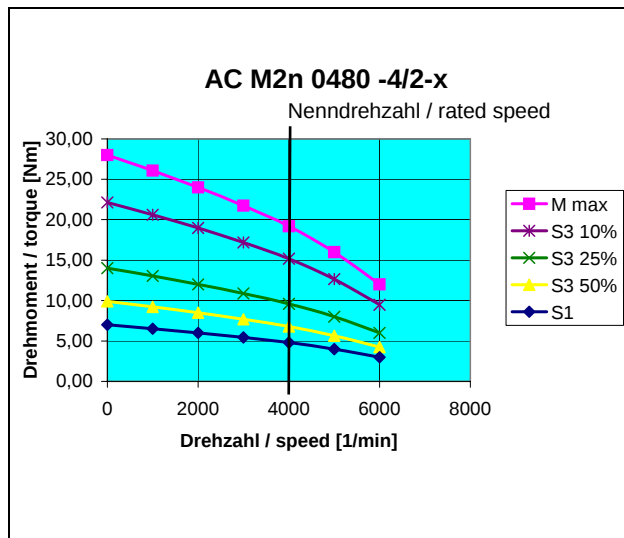
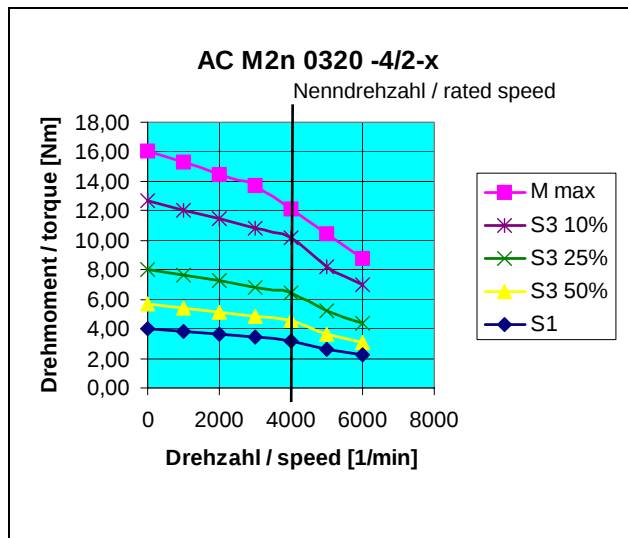
3.1.2 Motor size 1



Technical data

Torque/Speed Diagrams

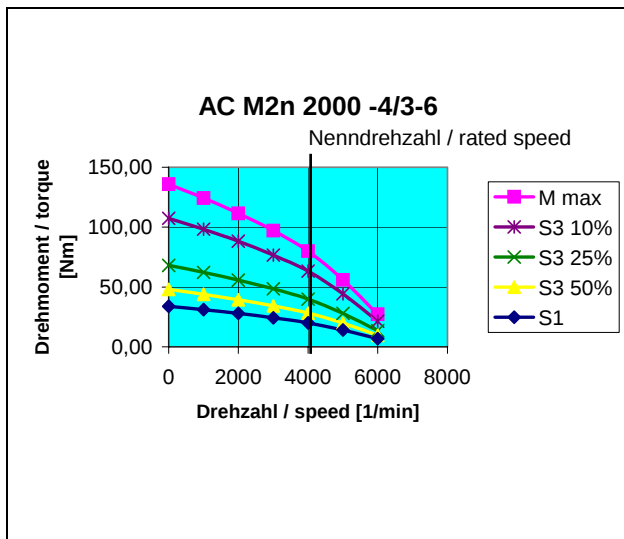
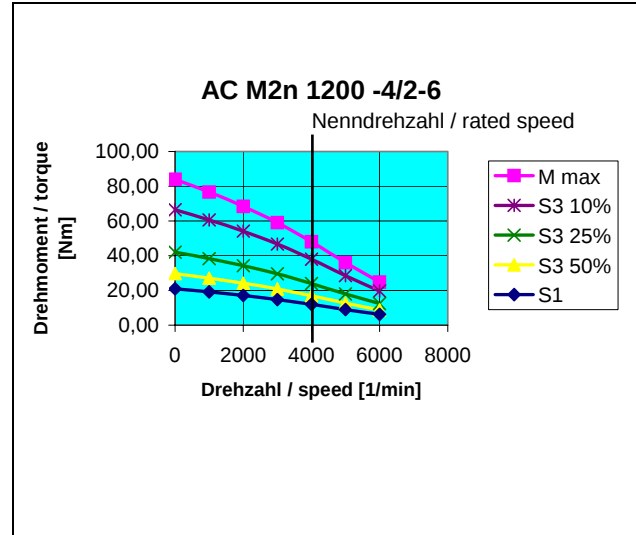
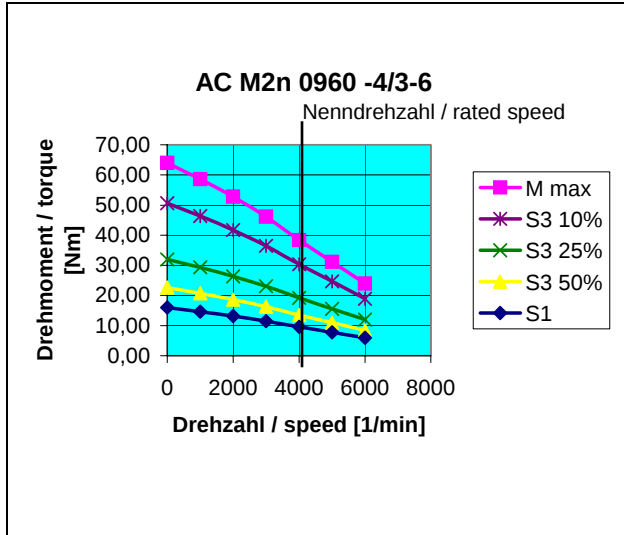
3.1.3 Motor size 2



Technical data

Torque/Speed Diagrams

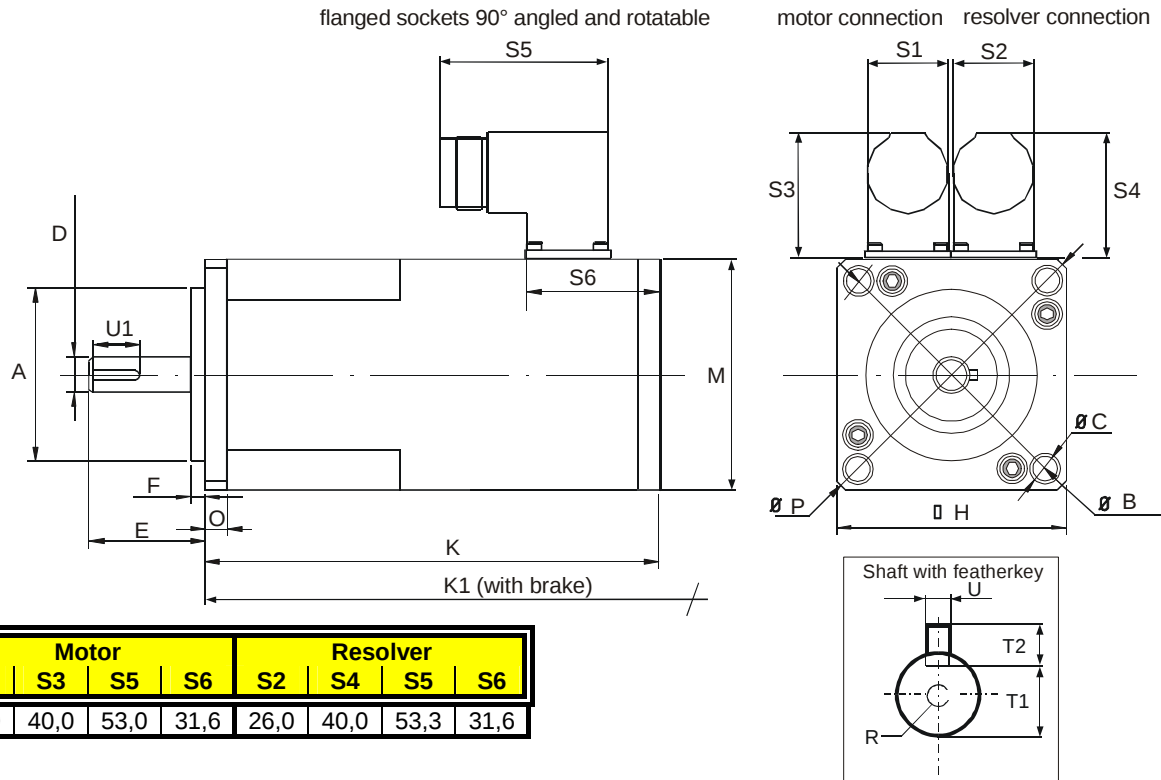
3.1.4 Motor size 3



4 Dimensions

4.1 Standard design Motor size Y...3

4.1.1 Connections via connectors



model	size	A (j6)	B	C	D (k6)	E	F	H	K	K1	M	O	P	R	T1	T2 (h9)	U (h9)	U1
AC M2n0012.. ⁴⁾	Y	30	46	4,3	6	20	2,5	40	130	-	40	0	54	-	-	-	-	-
AC M2n0010..	0	40	63	5,8	9	24	2,5	55	98	131	55	8	74	M3-10	7,2	3	3	14
AC M2n0030..		40	63	5,8	9	24	2,5	55	123	156	55	8	74	M3-10	7,2	3	3	14
AC M2n0045..		40	63	5,8	9	24	2,5	55	143	176	55	8	74	M3-10	7,2	3	3	14
AC M2n0070..		40	63	5,8	9	24	2,5	55	163	196	55	8	74	M3-10	7,2	3	3	14
AC M2n0130.. ¹⁾		40	63	5,8	9	24	2,5	55	234	-	55	8	74	M3-10	7,2	3	3	14
AC M2n0055..	1	80	100	7	14	30	3	88	112	153	82	10	115	M4-12	11,1	5	5	20
AC M2n0090..		80	100	7	14	30	3	88	132	173	82	10	115	M4-12	11,1	5	5	20
AC M2n0150..		80	100	7	14	30	3	88	152	193	82	10	115	M4-12	11,1	5	5	20
AC M2n0220..		80	100	7	14	30	3	88	172	213	82	10	115	M4-12	11,1	5	5	20
AC M2n0290.. ²⁾		80	100	7	14	30	3	88	202	249	82	10	115	M4-12	11,1	5	5	20
AC M2n0290.. ²⁾		80	100	7	14	30	3	88	202	249	82	10	115	M4-12	11,1	5	5	20
AC M2n0320..	2	95	115	9	19	40	3	105	178	218	105	12	134	M6-15	15,5	6	6	30
AC M2n0480..		95	115	9	19	40	3	105	208	248	105	12	134	M6-15	15,5	6	6	30
AC M2n0650..		95	115	9	19	40	3	105	228	268	105	12	134	M6-15	15,5	6	6	30
AC M2n0830.. ³⁾		95	115	9	19	40	3	105	273	313	105	12	115	M6-15	15,5	6	6	30
AC M2n0960..	3	130	165	11	24	50	3,5	145	260	303	145	12	188	M8-25	19,9	7	8	40
AC M2n1200..		130	165	11	24	50	3,5	145	300	343	145	12	188	M8-25	19,9	7	8	40
AC M2n2000..		130	165	11	24	50	3,5	145	420	463	145	12	188	M8-25	19,9	7	8	40

¹⁾ not with holding brake equip

²⁾ K1 with 6 Nm holding brake

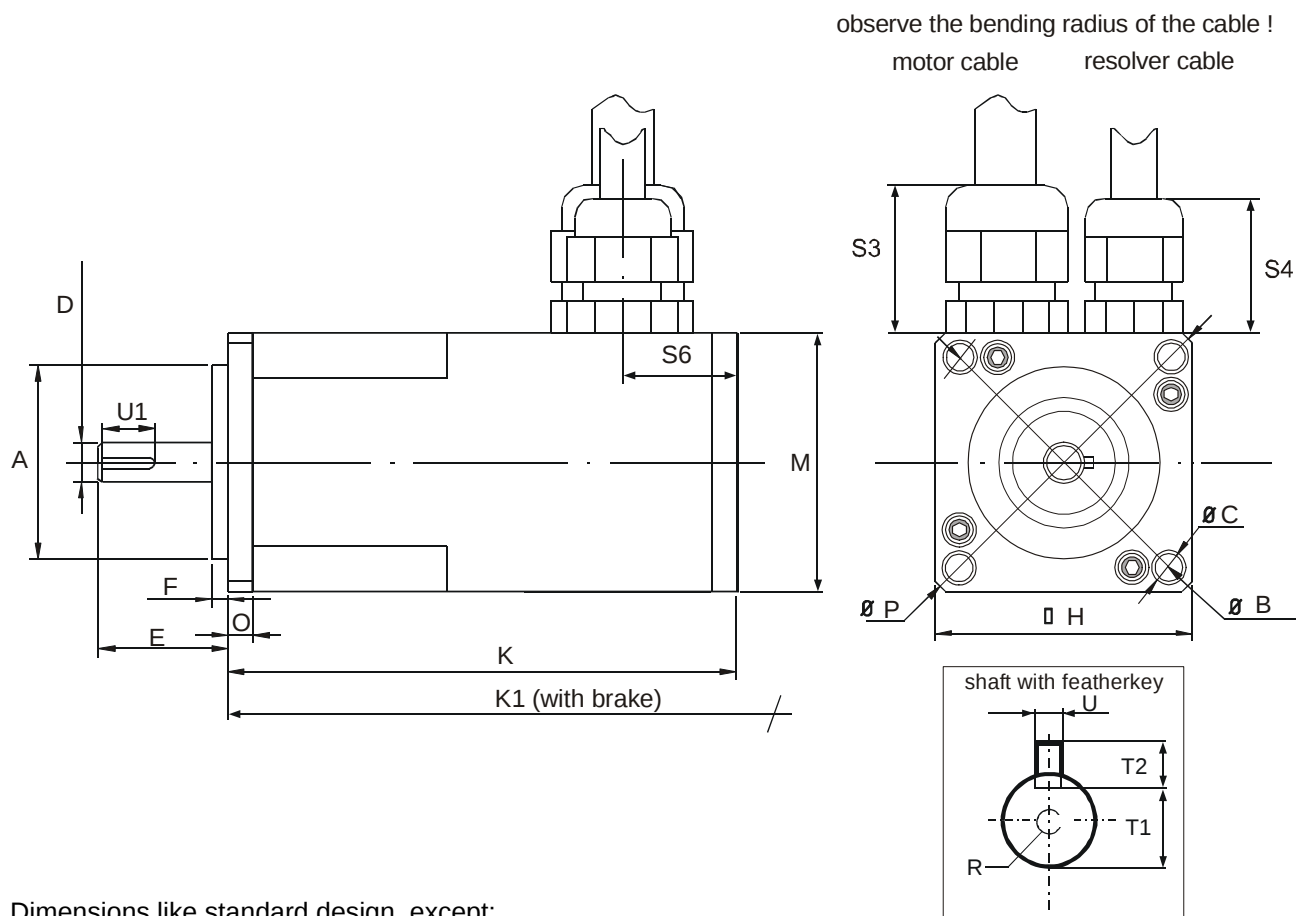
³⁾ design only with smooth shaft and PG coupling

all specifications in "mm"

Dimensions

4.2 Special design Motor size Y...3

4.2.1 Connections via PG couplings and cables



Dimensions like standard design, except:

AC <u>M2n</u> size	S3		S4		S6	Motor connection via PG coupling	Resolver connection via PG coupling	Comments
	Design Skintop	EMV	Design Skintop	EMV				
Y	25	-	22	-	16	-	-	cable low cost
0	28	21	25	20	18	13,5	9	-
1	28	21	25	20	18	13,5	9	-
2	28	21	25	20	20	13,5	9	-
3	-	-	-	-	-	-	-	Dimensions on request

Important !

- Observe the bending radius of the cables, see cable documentation **12-02-01** !

4.3 B - side Motor - mounting of Encodern

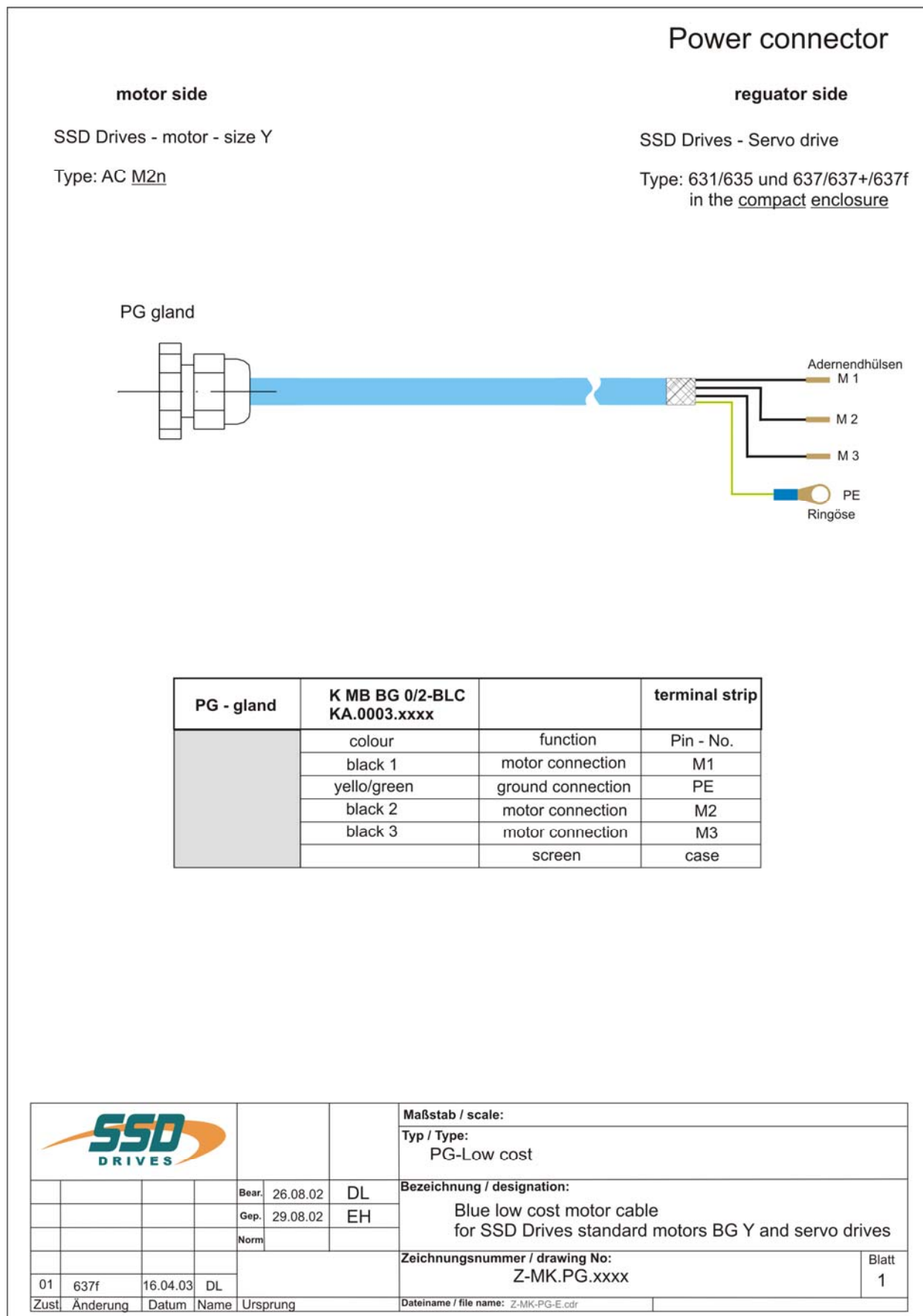
Please, request when required separate dimensional drawing.

Important !

- Additional connection plug connector or cable end
- Change of the engine length, dimension K or K1

5 Connector assignment

5.1 Connector



Connector assignment

Connector

Power connector

motor side

SSD Drives - motor size 0...2

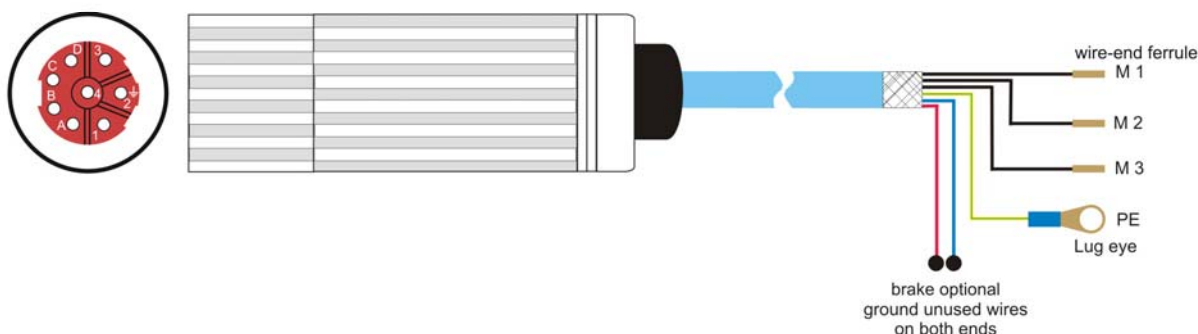
Model: AC G, AC M2n; ACM2G; AC M2K
AC MHS / MHM

regulator side

SSD Drives - Servo drives

Model: 631/635 and 637/637+/637f
637+/637f
in the compact enclosure

view solder / crimp connector - side



S MB GM2nRn BG 0/3-C+L ST.0100.3001		K MB BG 0/2-B KA.0003.6304		terminal strip	
PIN - Nr.		colour	function		PIN - Nr.
1		black 1	motor connection		M1
2	1)	yellow/green	ground connection		PE
3		black 2	motor connection		M2
4		black 3	motor connection		M3
A		red	brake +24V DC	2)	Connection
B		blue	brake 0V DC	2)	not on terminal
C		-	-		-
D		-	-		-
case	1)		screen		case

1) motor mating plug
the screen is connected to
the groundpin and also
extensively to the case.

2)  **Attention ! Security and insulation:**
The brake must be insulated for secure division (PELV). Otherwise,
the insulation class of the drive becomes reduced or the effort
of an additional galvanic separation is required.

				Maßstab / scale:	
				Typ / model:	
				KK MB GM2nRn 0/2.K - XX.X / B	
				Bezeichnung / designation:	
				Blue motor cable (compact enclosure) for SSD Drives standard motors and servo drives	
				Zeichnungsnummer / drawing No:	
				Z-MK.6400.xxxx	
				Blatt sheet	
				1	
Zust.	Änderung	Datum	Name	Ursprung	Dateiname / File name: Z-MK-6400-E.cdr

Connector assignment

Connector

Power connector

motor side

SSD Drives - motor size 3

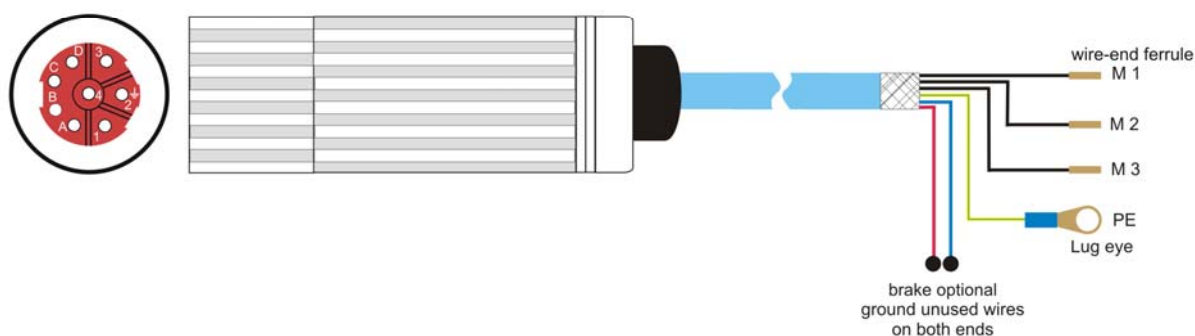
Model: AC M2n
AC MHS / MHM
AC MRW

regulator side

SSD Drives - Servo drives

Model: 631/635 and 637/637+/637f
637+/637f
in the compact enclosure

view solder / crimp connector - side



S MB GM2nRn BG 0/3-C+L ST.0100.3001		K MB BG 3-B KA.0003.6302		terminal strip	
PIN - Nr.		colour	function		PIN - Nr.
1		black 1	motor connection		M1
2	¹⁾	yellow/green	ground connection		PE
3		black 2	motor connection		M2
4		black 3	motor connection		M3
A		red	brake +24V DC	²⁾	Connection
B		blue	brake 0V DC	²⁾	not on terminal
C		-	-		-
D		-	-		-
case	¹⁾		screen		case

¹⁾ motor mating plug
the screen is connected to
the groundpin and also
extensively to the case.

²⁾  **Attention ! Security and insulation:**
The brake must be insulated for secure division (PELV). Otherwise,
the insulation class of the drive becomes reduced or the effort
of an additional galvanic separation is required.

Caution ! at X50 connector a terminal block must be employed

				Maßstab / scale:	
				Typ / model:	
				KK MB M2nRn 3	
				Bezeichnung / designation:	
				Blue motor cable for SSD Drives AC M2n size 3 motors and servo drives	
				Zeichnungsnummer / drawing No:	
				Z-MK.6401.xxxx	
				Blatt sheet	
				1	
01	637f	16.04.03	DL	Dateiname / File name: Z-MK.6401-E.cdr	
Zust.	Änderung	Datum	Name	Ursprung	

Connector assignment

5.2 X50 - connector

X50 - connector

motor side

SSD Drives - motor size 0...2

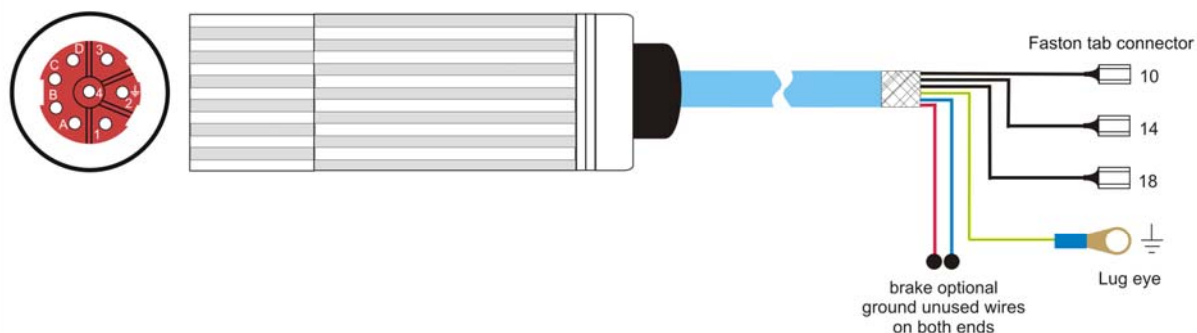
Model: AC M2n; ACM2G; AC M2K
AC MHS / MHM

regulator side

SSD Drives - servo drives

Model: 635 and 637/637+/637f
637+/637f
in the Rack

view solder / crimp connector - side



S MB GM2nRn BG 0/3-C+L ST.0100.3001		K MB BG 0/2-B KA.0003.6304		X50 connector strip		3)
PIN - Nr.		colour	function		PIN - Nr.	
1		black 1	motor connection		10	
2	1)	yellow/green	ground connection		12	
3		black 2	motor connection		14	
4		black 3	motor connection		16	
A		red	brake +24V DC	2)	18	
B		blue	brake 0V DC	2)	20	
C		-	-		-	
D		-	-		-	
case	1)		screen		case	

1) motor mating plug
the screen is connected to
the groundpin and also
extensively to the case.

2)  **Attention ! Security and insulation:**
The brake must be insulated for secure division (PELV). Otherwise,
the insulation class of the drive becomes reduced or the effort
of an additional galvanic separation is required.

3) not in the
Scope of delivery

				Maßstab / scale:	
				Typ / model:	
				KK MB GM2nRn 0/2.R - XX.X / B	
				Bezeichnung / designation:	
				Blue motor cable (plugs/terminal strip) for SSD Drives standard motors and servo drives	
				Zeichnungsnummer / drawing No:	
				Z-MK.0400.xxxx	
				Blatt sheet 1	
Zust.	Änderung	Datum	Name	Ursprung	Dateiname / File name: Z-MK-0400-E.cdr

Connector assignment

5.3 Resolver connector

Resolver connector

motor side

SSD Drives - motor size 0...4

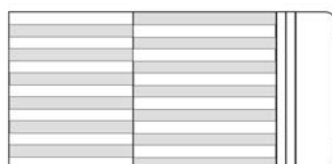
Type: AC G, AC R, AC Mn,
AC M2n, AC M2K; ACM2G
AC MRW, AC MRL

regulator side

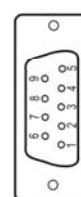
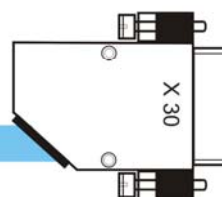
SSD Drives - servo drives

Model: 631/635 and 637/637+/637f

view solderside



view solderside



SIR ST.0200.0001	KIR -B KA.0003.6301		SUB - D 09 S/M ST.1002.2001
PIN - Nr.	colour	function	PIN - Nr.
1	white	sin +	4
2	brown	sin -	8
3	green	cos +	3
4	yellow	cos -	7
5	red	PTC optional	2
6	blue	PTC optional	6
7	pink	carrier -	9
8	gray	carrier +	5
case		screen	case

				Maßstab / scale:			Typ / model:	
							KK RT GMR-xx.x/B	
05	ACM2K	10.08.04	DL	Bear.	09.05.01	DL	Bezeichnung / designation: Blue resolver cable for SSD Drives standard motors and servo drives	
04	ACMRL	27.11.03	DL	Gep.	10.05.01	EH		
03	ACMRW	02.10.03	DL	Norm				
02	ACM2G	15.08.03	DL					
01	637f	16.04.03	DL				Zeichnungsnummer / drawing No:	
							Z-RK.6300.xxxx	
Zust.	Änderung	Datum	Name	Ursprung	Dateiname / File name: Z-R-6300-E.cdr			Blatt sheet 1

Connector assignment

5.4 Cabling instructions

Important rules when operating servo regulators and servomotors:

1. A radio interference suppression level cannot be maintained without an interference suppression filter at the line input. Moreover, line filter increase the immunity of the system to interference.
2. The cable between the power electronics and the motor must be shielded as YCY. A SY shield is not suitable. The shield support for the power cable (motor cable) must be on both ends. We recommend using SSD Drives motor cables K M BG xx – B!
3. Metal parts in the switching cabinet must be connected with each other having large areas of contact and must carry high frequencies very well. Avoid anodized, yellow-passivized and painted surfaces which can have very high resistance values based on the frequency! Make sure that the metals lie close together in the chemical circuit voltage class! Use the good conductivity and the large surface of the galvanized mounting plate as earth potential!
4. Relays, contactors and solenoid valves build into the same circuit must be connected with spark-suppressing combinations or components limiting over voltage, respectively. This applies also if these parts are not mounted in the same cabinet as the servo regulator.
5. The shield for the analog signal lines must be installed on one end and, if possible, in the switching cabinet. Ensure a connection which provides extensive contact and which is low-resistant! The shield for the digital signal lines must be installed on both ends, must have extensive contact and must be low resistance. An additional equalizer is to be laid parallel when there are potential differences. It is necessary to use plugs with metal enclosures with separable connections.
6. Avoid unnecessary extra loops on all connecting cables. All measures regarding filtering and shielding can be short circuited on them with high frequency. Connect unused litz wires in cables on both ends to the equipment ground conductor.
7. Unshielded cables of a circuit, the conductors going out and returning, should be twisted due to symmetrical interferences.
8. Separate physically "live" and "dead" wires even in the planning phase. Give special attention to the motor cables. The area of the common terminal strip-line input and motor output is especially endangered.
9. Relays, contactors and solenoid valves. The cables should be laid in the switching cabinet as close as possible to the ground; wires hanging freely in the air are preferred EMC victims as well as active and passive aeriels.
10. When operating with more than one line component in a common network, EMC problems are to be expected. From the start, the installation planner must integrate in his concept high frequency emitted interference as well as the electromagnetic susceptibility of the components to one another and take measures against it.
11. It is absolutely necessary to run cable shields completely up to the connectors. The connection of the cable shields to ground must be in the near field of the servo regulator (10 - 50 cm). Sensitive measuring leads should be removed as far as possible from this area; this applies also when they are shielded!
12. It is mandatory to run the motor cables in a separate cable channel and to lay flexible cable shielding also when these are shielded. This channel must be separated by at least 30 - 40 cm from the channel for the signal lines.

Connector assignment

5.5 Plug designation

5.5.1 Mating plugs for motor- and brake connections

Size	Plug designation
Y	only with wire-end ferrule
0...3	S MB G M2nRn 0/3

5.5.2 Mating plugs for resolver- and thermal connection

Size	Plug designation
Y	PG – coupling
0...3	SIR

5.6 Cable designation

5.6.1 Motor-cable

Size	Cable designation
Y...2	K MB R BG 0/2 – B K MB R BG 0/2 – B – LC*
3	K MB R BG 3 – B

5.6.2 Resolver-cable

Size	Cable designation
Y...3	K IR – B K IR – B – LC*

* LC = low cost cable

6 Technical data of the holding brake

optional

holding brake	motor size	holding torque	max. current	moment of inertia	weight
Typ:	BG	M _{BrH}	I _{max}	J _{Br}	m _{Br}
	(-)	(Nm)	(A)	(kg cm ²)	(g)
BR M BGY	¹⁾ Y	-	-	-	-
BR M BG0	¹⁾ 0	0,75	0,33	0,003	190
BR M BG1	1	3,20	0,42	0,030	445
BR M BG2	2	6,00	0,55	0,630	700
BBR M BG3	3	20,00	0,80	3,130	1040

¹⁾ Motor AC M2n0012 and AC M2n 0130 is not with holding brake equip !

²⁾ New type of brake BBR is used off approx. in the middle of 2003!

Supply voltage: $U_S = 24 \text{ V DC}$, $\pm 10\%$ acc. VDE 0580

Holding brakes are integrated on A- side; therefore the motor length is changed, see dimension K1 !

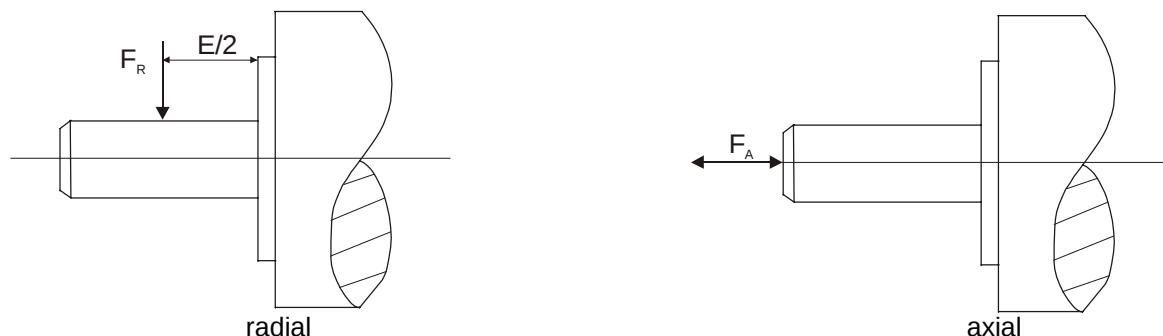
The inserted brake is not characterized for the general slowing-down the drives, but is merely a standstill and/or holding brake.

Therefore, it must become guaranteed by the customer, that the drive stands, before that brake comes in. Should that brake not only become employed in the case of standing drives, so it's generally the wear and therefore the holding torque of the brake depending on:

- the speed of the drive with which the brake will be switched
- the load moment of inertia on the drive
- environmental conditions as temperature, and so forth.
- the number of braking and so forth

7 Shaft loads

7.1 Notation of definition



7.2 Technical dates of the max. radial F_R (N) and axial F_A (N) shaft load

Motor-Type	rated speed I	maximum radial shaft load	maximum axial shaft load
(-)	n_n (1/min)	F_R (N)	F_A (N)
AC M2n 0012	6000	51	72
AC M2n 0010	4000	220 (138)	80 (33)
AC M2n 0030	4000	220 (155)	80 (33)
AC M2n 0045	4000	220 (163)	80 (33)
AC M2n 0070	4000	220 (169)	80 (33)
AC M2n 0130	4000	220 (175)	80 (33)
AC M2n 0055	4000	250 (156)	90 (45)
AC M2n 0090	4000	250 (171)	90 (45)
AC M2n 0150	4000	250 (181)	90 (45)
AC M2n 0220	4000	250 (189)	90 (45)
AC M2n 0290	4000	250 (195)	90 (45)
AC M2n 0320	4000	300 (333)	100 (71)
AC M2n 0480	4000	300 (346)	100 (71)
AC M2n 0650	4000	300 (362)	100 (71)
AC M2n 0830	4000	300 (391)	100 (71)
AC M2n 0960	4000	570 (383)	200 (83)
AC M2n 1200	4000	570 (398)	200 (83)
AC M2n 2000	4000	570 (427)	200 (83)

The values in bracket relate to simultaneous radial and axial shaft loads.

The specifications refers to 20000 hours of operation !

7.3 Use Ball bearing type

Motor-size	Ball bearing type	
	A-side	B-side
Y	607	607
0	6001	6001
1	6003	6001
2	6004	6002
3	6205	6004

8 Nominal power dependence of the SSD Drives AC servo motors concerning the installation altitude

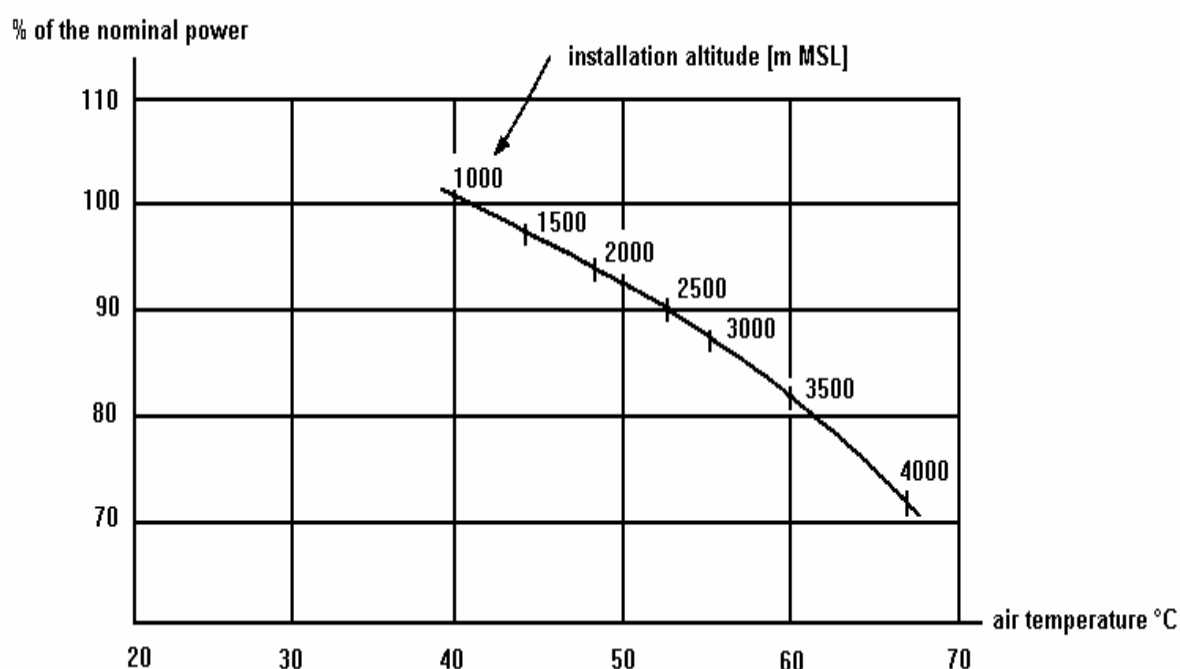
8.1 Short description

When selecting an adequate motor the following is to be considered:

Workload (power), operating mode, starting, braking and by-passing processes, additional moment of inertia, moment course of the operating machine, speed control if necessary, net ratios, coolant temperature, installation altitude etc.

The nominal power is the power which is mechanically available at the shaft, if the installation site is not situated above 1000 m MSL, the air temperature does not exceed 40° C, and the net ratios are normal.

With deviating conditions concerning installation altitude and air temperature, the permissible power must be corrected corresponding to the following picture.



Check the air temperature and the installation altitude separately. Should there be different air temperatures and installation altitude at the same time, the factors for the permissible power must be multiplied.

9 Certificates



Standard Specifications and Certifications Manufacturer's Declaration

**In accordance with the EC – Machinery Directive 89/392/EEC
Annex II B approximation of the regulation of the member states for machinery.**

The following Products

AC – Servo - motors of series

AC M2n, AC M2K, AC MHx, AC M2G and AC G

in standard design are components to be incorporated into machinery and may not be operated alone. The complete machinery or installation using this equipment may only be put into service when the safety considerations of the Directive 89/3892/EEC are fully adhered to.

The above mentioned products are in accordance with the relevant clauses from the following standards.

Basic directives:

- EN 60034 / VDE 0530
- IEC 34 – 1,5,6,8,9,14 / IEC 72 / IEC 85
- VDE 0100, VDE 0110, VDE 0530-1
- EC – MASCHINERY DIRECTIVE 89/392/EEC
- EC – LOW VOLTAGE DIRECTIVE 73/23/EEC

CE – Lable
as standard on the name plate.

Issuer:

SSD Drives GmbH
Im Sand 14
76669 Bad Schönborn

Bad Schönborn, 01.11.2004

Legally binding signature


ppa. Erich Ehlen
Plant Manager

This declaration does not include any assertion of properties. The references for safety and protection (operating instruction) are to observe in every case keep.

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