## Objective

620L to 690+ wiring information

## Equipment

690+ AC Drive, Systems Board (factory installed), 6053/6055-L-00 (Link Techbox), computer with DSD-DEV (> v.1.14) installed, assorted hand tools, 24 Vdc supply rated for one amp.

Note: This document is intended for users with previous experience of developing Link drive systems.

## Procedure

1. Remove all power to the 620 drive.
2. Uninstall the 620 drive.
3. Install the 690+ drive that includes a systems board with a Link Techbox attached.

Note: Connect only the 3-phase input AC voltage wiring. Also, remember to add a fiber optic jumper to Link Techbox for completion of the Link network
4. Apply the AC power to the 690+ drive.

Note: The user must have Drive Systems Designer Development (DSD-DEV) software to configure the 690+ drive.
5. Create a 690+ file using DSD-DEV to download into the Link Techbox.
**Warning: Adjustments to the drive software configuration are needed. The DSD template needs to be verified for proper functionality.
** Hint** The digital inputs on the 620L drive were connected to the Preset block.
However, only Dig In 7 and Dig In 8 on the 690+ are connected to the Sequencing Logic block. All other I/O points are not configured by default.
6. After verifying the downloaded Link configuration, remove the AC power from the $690+$ drive.
7. Install all power connections.

Note: Remember the 24 Vdc supply is for the Systems board only.
8. Using the chart below convert the wiring changes from the 620L terminals to the 690+ terminals.

Note: The Thermistor connection has been replaced with the External Trip.
Note: Verify all control and power connections.
9. Re-apply the AC power.
10. Use 690+ quick start for basic motor operation.

Related Documents:
690+ (Frame B - F) Install manual HA465492
690+ Software manual HA465038
Application Notes 3408
If you have questions, please call the Product Support Group at (704) 588-3246.

## Application Note

Product:
690+
557.

Document Number: 3411
Keywords: 620L to 690+
Wiring Information

| Terminal Description | $\begin{aligned} & \text { 620L Terminal } \\ & \# \end{aligned}$ | $\begin{gathered} 690+ \\ \text { Terminal \# } \end{gathered}$ | Terminal Description | $\begin{aligned} & \text { 620L Terminal } \\ & \# \end{aligned}$ | $\begin{gathered} 690+ \\ \text { Terminal \# } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Feedback Channel A | A1 | Systems Board C 1 | Reference Channel A | D1 | Systems Board B2 |
| Feedback Channel A comp. | A2 | Systems Board C 2 | Reference Channel A comp. | D2 | Systems Board B3 |
| Feedback Channel B | A3 | Systems Board C 3 | Reference Channel B | D3 | Systems Board B4 |
| Feedback Channel B comp. | A4 | Systems Board C 4 | Reference Channel B comp. | D4 | Systems Board B5 |
| Feedback Channel Z | A5 | Systems Board C 5 | Reference Channel Z | D5 | Systems Board B6 |
| Feedback Channel Z comp. | A6 | Systems Board C 6 | Reference Channel Z comp. | D6 | Systems Board B7 |
| Encoder Supply | A7 | Systems Board B8 | Encoder Supply | D7 | Systems Board B8 |
| Encoder 0v | A8 | Systems Board B9 | Encoder 0v | D8 | Systems Board B9 |
| Ground | A9 | Systems Board A1 | Ground | D9 | Systems Board A1 |
| Thermistor 0v | B1 | Motor Therm | 0v | E1 | 11 |
| Thermistor Input | B2 | Motor Therm | Digital In 1 | E2 | 12 ** |
| Health Output | B3 | 21,22 | Digital In 2 | E3 | $13^{* *}$ |
| Coast Stop | B4 | 19 | Digital In 3 | E4 | $14^{* *}$ |
| Fast Stop | B5 | 18 | Digital In 4 | E5 | 15 ** |
| Jog | B6 | 16 | Digital Out 1 | E6 | 23, 24 |
| Start | B7 | 12 | Digital Out 2 | E7 | 21, 22 |
| Enable | B8 | 17 | Digital Out 3 | E8 | 25, 26 |
| 24V Supply | B9 | 20 | +24V | E9 | 20 |
| Ground | C1 | 1 | 0V | F1 | 1 |
| Signal 0v | C2 | 1 | Analog In 3 | F2 | 4** |
| Ramp Input | C3 | 2 | Analog In 4 | F3 | 5 ** |
| Direct Input | C4 | 3** | Analog In 5 | F4 | -- |
| Analog Out 1 | C5 | 6 | Analog Out 2 | F5 | 7 |
| +10V Supply | C6 | 9 | -10 V Supply | F6 | 9 |

** Configurable Input

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